

PCAN-MIO

Universal Controller
for CAN Applications

User Manual



Document version 1.15.0 (2023-05-09)

PEAK
System

Relevant Products

Product Name	Model	Part number	Firmware version
PCAN-MIO	Industrial connector (Phoenix)	IPEH-002187	3.4.x (from ser. no. 100)
PCAN-MIO	Automotive connector (Tyco)	IPEH-002187-A	

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1 Introduction

The Multiple Input Output module (MIO) is a universal, modular controller for use both in the industrial and automotive fields.

The module has two CAN interfaces as well as multiple analog and digital inputs and outputs. Incoming signals can be processed by the microcontroller and then forwarded to the CAN interfaces or output channels. For this purpose, the behavior of the PCAN-MIO module can be freely configured using comprehensive Windows software. A large number of function blocks and other settings are available to help the user in creating such a configuration.

Pluggable CAN transceiver modules allow flexible adaptation of each CAN channel to the respective requirements. For example, Low-speed and Single-wire CAN transceivers are also available on request.

1.1 Properties at a Glance

- └ 2 High-speed CAN channels (ISO 11898-2)
 - Comply with CAN specifications 2.0 A/B
 - CAN bit rates from 40 kbit/s up to 1 Mbit/s
 - NXP TJA1041 CAN transceiver with wake-up
 - Alternative pluggable transceiver modules on request
- └ CAN termination switchable
- └ Wake-up function using separate input or CAN bus
- └ 8 digital inputs with low-pass performance
- └ 8 digital outputs, 2 of them PWM-capable

- └ 6 analog inputs, measuring range unipolar 0 to 10 V, resolution 10 bit, sample rate 1 kHz
- └ 2 analog outputs, 0 to 10 V, each 20 mA, resolution 10 bit
- └ Suitable for use in the automotive field
- └ Detailed configuration with the Windows software PPCAN-Editor 2
- └ Module can store up to 15 configurations
- └ CAN gateway between the buses
- └ Various function blocks for data linking and modification
- └ Available with industrial connectors (Phoenix spring terminal connectors) or automotive connectors (Tyco connectors)
- └ Aluminum profile casing with mounting flange
- └ DIN rail mounting option on request
- └ 9 to 27 V voltage supply, overvoltage and reverse polarity protection
- └ Extended operating temperature range of –40 to +85 °C (–40 to +185 °F)

1.2 Operation Requirements

- └ Power source, nominal 12 V DC, 9 to 27 V possible

For the configuration:

- └ Computer with Windows 11 (x64/ARM64), 10 (x86/x64)
- └ PC CAN interface from PEAK-System (in scope of supply when ordering the Set)
- └ CAN cabling with correct termination

1.3 Scope of Supply

- └ PCAN-MIO basic module in aluminum casing
- └ 4 spring terminal strips 11-pin (industrial model IPEH-002187)¹
- └ 32-pole and 12-pole plug with crimp contacts (automotive model IPEH-002187-A)¹
- └ CAN interface PCAN-USB with order of the Set

Downloads:

- └ Configuration software PPCAN-Editor 2 for Windows
- └ Documentation in PDF format

¹ Connector types: see technical specifications on page 29

2 Function Characteristics of the Basic Module

This chapter describes the essential functional characteristics of the PCAN-MIO basic module.

There is a list of all logical resources (I/O function, I/O number) which are provided by the PCAN-MIO module in the Appendix D on page 37.

2.1 Supply

The internal 5-Volt supply is provided by a switching regulator. This regulator also meets the 5-Volt needs of additional boards and external low-power consumers such as sensors. The dimensioning covers an overall need of 2 A.

At the power input protection is provided against overvoltage and reversed polarity. With the help of two internal control lines the microcontroller can switch internal consumers on or off and activate self-holding. To handle brownouts, a comparator checks the internal 5-Volt supply and triggers a reset if necessary (smaller than 4.35 V). The CAN transceiver modules are wake-up-capable and are permanently supplied with input voltage.

The PCAN-MIO module can be activated by an external control connection as an alternative to the CAN wake-up. After booting the microcontroller can itself control the power supply by means of the already mentioned self-holding. External sensors are supplied with 5 V, protected and loadable to a max. of 500 mA. In case of a short-circuit the continued work of the microcontroller is assured by the decoupling of the internal 5-Volt supply. A reference of 5 V is provided for analog, internal use.

2.2 Analog Inputs

There are six analog inputs with pull-down circuit (12 k Ω), low-pass performance and overvoltage protection. The default measuring range is from 0 to 10 V. Analog measurements are unipolar, single-ended, have a resolution of 10 bit (A/D converter) and referenced to a 5 V, 0.2 % accuracy and a temperature coefficient of 20 ppm.

The measuring range for the individual inputs can be adapted by a voltage divider. Regarding this subject please contact PEAK-System (contact information: see **Fehler! Textmarke nicht definiert.**).

2.3 Analog Outputs

The two analog outputs are derived from a 10-bit D/A converter. The standard output voltage is 0 to 10 V for a maximum current drain of 20 mA. The outputs are short-circuit-proof. As an option, instead of the internal reference of 5 V, the supply voltage VE can be specified as a reference (hardware modification required). In this case, the internal reference is 1/3 of the supply voltage VE, however, it is limited to 5.1 V.

The internal reference is used as a standard. Regarding the optional external reference please contact PEAK-System (contact information: see **Fehler! Textmarke nicht definiert.**).

2.4 Digital Inputs

There are eight digital inputs with low-pass performance and hysteresis behavior. In groups with one, two or three inputs, pull-up and pull-down resistors can be connected, for example for contacts.

The switch thresholds are 4 V (High) and 3 V (Low). For the power-save mode the pull-up circuits can be shut down by the microcon-

troller. The inputs DIN0 to DIN4 are connected directly to the input-capture pins of the microcontroller as fast inputs to determine frequencies and the duty cycles. The DIN5 to DIN7 inputs are for the static status recognition (max. possible switching frequency: approx. 1 kHz).

2.5 Digital Outputs

The eight digital outputs are subdivided into six protected, statically addressable low-power switches (DOUT2 to DOUT7, max. 0.6 A) and two protected, PWM-capable high-side switches (DOUT0 and DOUT1, max. 1.4 A). The high-side switches are allocated to PWM-capable timer outputs (HW-PWM). In the case of the low-power switches, a configuration can be used to decide for each output whether it should work as high-side or low-side switch or be inactive. When used as low-side switch, an output can be operated with up to 30 V against ground.

The protective measures relate to excessive voltage, current, and temperature. The high-side switch is supplied with power directly from the module's power connection. Protection is provided against reverse poling of the supply voltage.

2.6 Function Blocks

This table is an overview of the various function blocks available for processing the data with the microcontroller.

You can obtain details about the individual function blocks from the reference tables which come with the configuration program PPCAN-Editor for Windows which is included in the delivery.

Function block	Description
Identity	Copies the input variable to the output variable.
Scaling	Conversion of an input value, with multipliers and offset; the result is copied into the output variable.
Hysteresis	The output is dependent on the input value set to one of two pre-defined values.
Monoflop	The output is set to one of two pre-defined values depending on the input value for a pre-defined period.
Extended Hysteresis	Depending on an input value the output is timeout activated for a pre-defined period (set to 1). A second input acts as an enable signal.
Switch Delay	Switch-on, switch-off delay or a combination of the two.
Lowpass	Realization of a lag element by a low-pass with an adjustable time.
Characteristic Curve	The input signal is converted by applying a pre-defined characteristic curve.
Characteristic Curve with Limit	Like the characteristic curve but in this case values specified outside the characteristic curve are returned.
Characteristic Map	The input signal is converted using a pre-defined surface which is composed from a list of characteristic curves.
Characteristic Map with Limit	Like the characteristic map but in this case values specified outside the surface are returned.
Small Map	The two inputs indicate a position within a grid of 12 fields. The return values of the fields are specified by the default assignment tables.
Ramp Counter	Each time a function is called the counter counts one more step from a lower to an upper limit and then begins again at the lower value.
Counter with Clock and Reload Input	Counter for flanks to an input
PI Element	Simple PI regulator with reference and actual value inputs
PIDT1 Element	PIDT1 regulator
Difference	Help function block for the PIDT1 regulator
Math Function	Collection of various mathematical and logical functions
Binary Field	Compiles a sequence of digital data into a binary value.

2.7 PPCAN Protocol

The PCAN-MIO module is configured via a connected CAN bus per PPCAN protocol (point-to-point CAN), a development achieved by PEAK-System Technik GmbH. The PPCAN protocol permits as a principle the data communication between two specified CAN nodes, i.e., CAN data are transmitted to a specific target. In this way configuration data transmissions can be directed to one PPCAN-capable module or to a transmitted PCAN-MIO module on the CAN bus.



Note: The PPCAN protocol uses the **CAN ID 7E7h** for communication. Do not use this CAN ID for further communication of CAN nodes in a net.

2.8 Module Reset

The module has no separate switch or input for a reset. You can reset the PCAN-MIO module by separating it for a short time from the supply. An option for switching off, for example, is the selfhold function controlled via CAN; the subsequent restart can be triggered by a wake-up signal.

3 startup

This chapter describes the preparations necessary to ensure that the PCAN-MIO module can receive and transmit data via a connected CAN bus. This section does not yet discuss how to create and apply a configuration. There is a guide on this subject in the help pages provided with the Windows-based PPCAN-Editor.

The description assumes that you initially connect only one PCAN-MIO module via a High-speed CAN bus to a PC with a Windows operating system.

Please read through all the sections in this chapter.

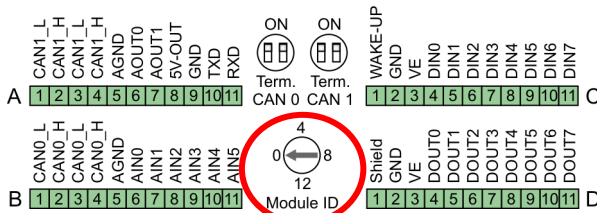


Note: For the configuration of the PCAN-MIO module, a CAN interface of the PCAN series (e.g. PCAN-USB) is required.

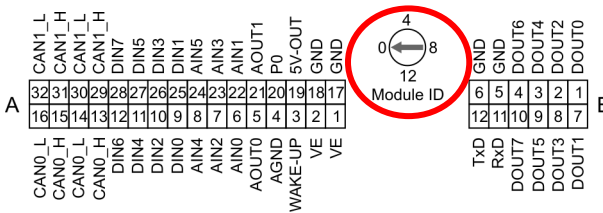
3.1 Module Settings

Settings for the module ID and a CAN termination can be made using switches on the PCAN-MIO module.

Please check that the rotary switch for the **Module ID** is set to **0**.

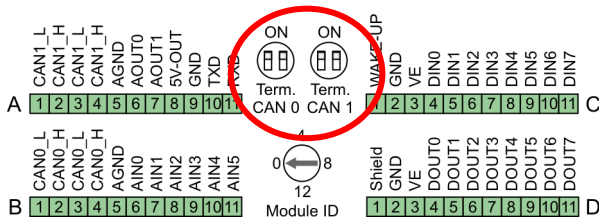


Rotary switch for the module ID on the front plate of the industrial model

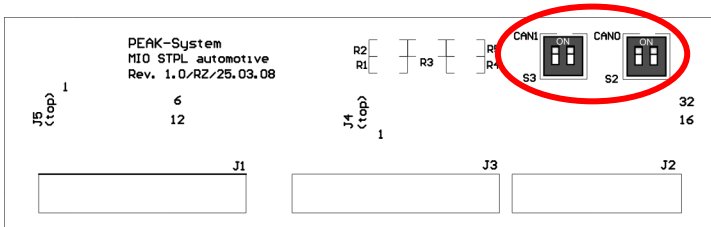


Rotary switch for the module ID
on the front plate of the automotive model

Since in the assumed case the PCAN-MIO module is the sole node on the High-speed CAN bus connected via a direct line to the CAN interface of a PC, the **termination** must be activated. The two DIP switches on the switch block for CAN 0 must be in the upper position **ON**.

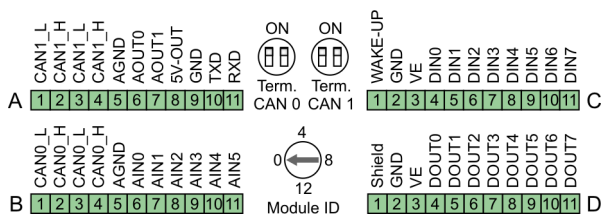


Switch blocks for the CAN bus termination
on the front plate of the industrial model

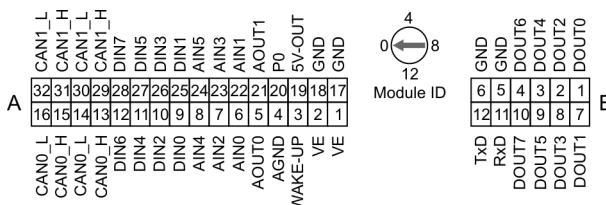


Switch blocks for the CAN bus termination (automotive model),
rear side of the connector board when the PCAN-MIO housing is open

3.2 Basic Connections



Connector pin assignment industrial model



Connector pin assignment automotive model

The following pins are used to connect the **CAN bus**:

Line	Connection Industrial	Connection Automotive	Comment
CAN0_L	B1/B3	A14/A16	Ports with the same signal name are internally connected.
CAN0_H	B2/B4	A13/A15	

The operation of the PCAN-MIO module requires a **voltage source** with a nominal 12 V direct current voltage (9 - 27 V possible). The connection is made using these pins:

Line	Connection Industrial	Connection Automotive	Comment
GND	C2/D2	A17/A18	Ports with the same signal name are internally connected.
VE	C3/D3	A1/A2	

When supply voltage is present, the module starts operation only on a wake-up signal. Depending on the CAN transceiver equipment

this happens automatically, or you have to apply a High stage to the external wake-up line.

Line	Connection Industrial	Connection Automotive
WAKE-UP	C1	A3

The PCAN-MIO module has started operation as soon as the **status LED** blinks green.

3.3 Output States at Power-up

After powering up the module and before a configuration is read from the EEPROM the outputs have the following states:

Outputs	State
DOUT	high impedance (tri-state)
AOUT	0 V
5V-OUT	high impedance (tri-state)

3.4 Software Installation

The module is configured using the included PPCAN-Editor, which runs on a Windows platform, via a CAN bus connection between the computer with CAN interface from PEAK-System and the PCAN-MIO module.

▶ This is how to install the PPCAN-Editor:

1. Download the software package with the setup program for the PPCAN-Editor 2 from our website. On the following download page you will find the corresponding entry:
www.peak-system.com/quick/DL-Software-E

2. Unpack the downloaded `ppcanedit.zip` file.
3. From the unpacked folder, start the setup program `PPCAN-Editor2-Setup.exe`. Confirm the possible request of the user account control.
4. Follow the instructions of the setup program.

You can then launch the PPCAN-Editor, create a configuration, and transmit this to the PCAN-MIO module. Find relevant information in the help of the PPCAN-Editor. See also some introductory video tutorials to the PPCAN-Editor in the Support area on our website (www.peak-system.com).



Note: The PPCAN-Editor uses the **CAN ID 7E7h** for communication with the PCAN-MIO module. Do not use this CAN ID for further communication of CAN nodes in a net.

3.5 Altered Configuration Structure from Serial Number 100

From serial number 100 PCAN-MIO modules work with an internally altered configuration structure. Therefore, at creation of a new configuration in the PPCAN-Editor you must select the appropriate hardware profile:

PCAN-MIO serial number	MIO hardware profile to be used
up to 99	PCAN-MIO
from 100	PCAN-MIO (32-Bit)

Configurations being created based on the other MIO hardware profile cannot be directly sent to a PCAN-MIO module.

- ▶ Do the following to adapt a configuration to another MIO hardware profile:
1. In the PPCAN-Editor open the present MIO configuration.
 2. Select the menu command **Edit > New Configuration**.
The window for selecting a hardware profile is shown.
 3. Depending on the MIO hardware profile used presently select the other one. When updating to a PCAN-MIO module with serial number 100 and up, this is **\$1B PCAN-MIO (32-Bit)**, in the vice versa case accordingly **\$14 PCAN-MIO**.
 4. Create the module-specific CAN configuration on the new tab in the window **CAN Objects**. This is done on basis of the **General** CAN objects. When matching the entries, you can use the previous module-specific CAN configuration for orientation.
 5. Open the configuration windows of the previous and the new configuration (**Config XY**).
 6. From each tab of the present configuration, copy all entries onto the tab of the new one. You can use the known key shortcuts for selecting, copying, and inserting under Windows.
 7. In the **CAN Objects** window, delete the former configuration by executing the corresponding context menu command on the configuration's tab.



Note: New I/O functions which are only available in the hardware profile “\$1B PCAN-MIO (32-Bit)” cannot be copied to configurations based on the profile “\$14 PCAN-MIO”.

4 Front Panel Elements

This chapter describes the elements present on the front of the PCAN-MIO module housing. They involve connections, the switches for the CAN bus termination, the rotary switch to set the module ID and the status LED.

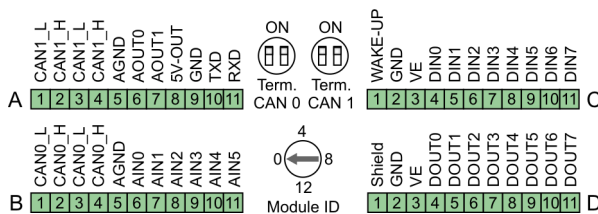
If you use an alternative plug-in board with an appropriately modified front panel the elements may be different from the standard elements mentioned here.

4.1 Pin Assignment

This section describes the functional assignment of all pin connections. There is a list of all logical resources (I/O function, I/O number) which are provided by the PCAN-MIO module in the Appendix D on page 37.

Ports with the same signal name are internally connected.

4.1.1 Industrial Connector (Phoenix)

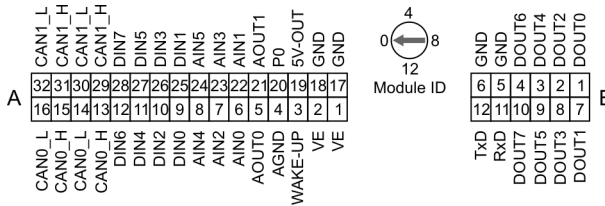


Connector pin assignment of the industrial model
(connector type: see technical specifications on page 29)

	Name	Use	More info
A			
1	CAN1_L	CAN connection transceiver 1	Connected to pin 3; at Single-wire CAN not connected
2	CAN1_H		Connected to pin 4
3	CAN1_L		Connected to pin 1; at Single-wire CAN not connected
4	CAN1_H		Connected to pin 2
5	AGND	Ground analog, reference for AOUT and AIN	
6	AOUT0	Analog Output 0 to 10 V, 20 mA, 10 bit	Only source
7	AOUT1		
8	5V-OUT	5 V, 500 mA	
9	GND	Ground, reference for digital and power supply	
10	TXD	RS-232	
11	RXD		
B			
1	CAN0_L	CAN connection transceiver 0	Connected to pin 3; at Single-wire CAN not connected
2	CAN0_H		Connected to pin 4
3	CAN0_L		Connected to pin 1; at Single-wire CAN not connected
4	CAN0_H		Connected to pin 2
5	AGND	Ground analog, reference for AOUT and AIN	
6	AIN0	Analog input 0 to 10 V	12 k Ω input impedance
7	AIN1		
8	AIN2		
9	AIN3		
10	AIN4		
11	AIN5		

	Name	Use	More info
C			
1	WAKE-UP	Digital input for wake-up signal	High (> 4.0 V) = module on
2	GND	Ground, reference for digital and power supply	
3	VE	Power supply 9 to 27 V DC	
4	DIN0	Digital input, optional determination of frequencies and duty cycles	High > 4.0 V, Low < 3.0 V 5 to 10,000 Hz Pull-up/Pull-down: up to ser. no. 99 by jumpers on the board (on request), from ser. no. 100 by configuration
5	DIN1		
6	DIN2		
7	DIN3		
8	DIN4	Digital input (static status detection)	Max. processible switch frequency < 500 Hz
9	DIN5		
10	DIN6		
11	DIN7		
D			
1	Shield	Shield	
2	GND	Ground, reference for digital and power supply	
3	VE	Power supply 9 to 27 V DC	
4	DOUT0	Digital output, high-side driver 5 A short circuit	Optional FOUT/PWM OUT with maximum frequency
5	DOUT1		
6	DOUT2	Digital output 0.6 A each 1.4 A together	Useable as high-side, low-side, or push-pull driver (by configuration) Low-side: max. 30 V against GND
7	DOUT3		
8	DOUT4		
9	DOUT5		
10	DOUT6		
11	DOUT7		

4.1.2 Automotive Connector (Tyco)



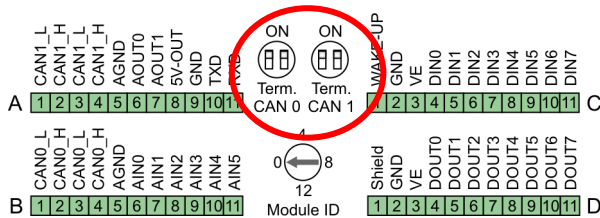
Connector pin assignment of the automotive model
(connector types: see technical specifications on page 29)

	Name	Use	More info
A			
1	VE	Power supply 12 V DC	KL30
2			
17	GND	Ground, reference for digital and power supply	KL31
18			
3	WAKE-UP	Digital input for wake-up signal	High (> 4.0 V) = module on
19	5V-OUT	5 V, 500 mA	
4	AGND	Ground analog, reference for AOUT and AIN	
20	P0	Reserved	
5	AOUT0	Analog Output 0 to 10 V, 20 mA, 10 bit	Only source
21	AOUT1		
6	AIN0	Analog input 0 to 10 V	12 kΩ input impedance
22	AIN1		
7	AIN2		
23	AIN3		
8	AIN4		
24	AIN5	Digital input, optional determination of frequencies and duty cycles	High > 4.0 V, Low < 3.0 V 5 to 10,000 Hz Pull-up/Pull-down: up to ser. no. 99 by jumpers on the board (on request), from ser. no. 100 by config
9	DIN0		
25	DIN1		
10	DIN2		
26	DIN3		
11	DIN4		

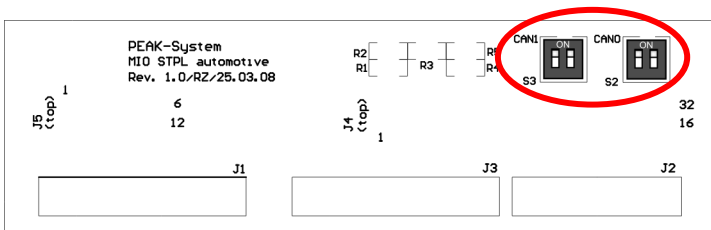
	Name	Use	More info
27	DIN5	Digital input (static status detection)	Max. processible switch frequency < 500 Hz
12	DIN6		
28	DIN7		
13	CAN0_H	CAN connection transceiver 0	Connected to pin 15
14	CAN0_L		Connected to pin 16; at Single-wire CAN not connected
15	CAN0_H		Connected to pin 13
16	CAN0_L		Connected to pin 14; at Single-wire CAN not connected
29	CAN1_H	CAN connection transceiver 1	Connected to pin 31
30	CAN1_L		Connected to pin 32; at Single-wire CAN not connected
31	CAN1_H		Connected to pin 29
32	CAN1_L		Connected to pin 30; at Single-wire CAN not connected
B			
1	DOUT0	Digital output, high-side driver 5 A short circuit	Optional FOUT/PWM OUT with maximum frequency
7	DOUT1		
2	DOUT2	Digital output 0.6 A each 1.4 A together	Useable as high-side, low-side, or push-pull driver (by configuration) Low-side: max. 30 V against GND
8	DOUT3		
3	DOUT4		
9	DOUT5		
4	DOUT6		
10	DOUT7		
5	GND	Ground, reference for digital and power supply	KL31
6			
11	RxD	RS-232	
12	TxD		

4.2 CAN Bus Termination (Switch)

Depending on the used CAN transceiver module you can activate or change a CAN bus termination with the corresponding switch blocks. Switches 1 and 2 on a switch block always must have the same position. By default the switches are in OFF position (lower position according to the orientation of the figure). The assignment of switch block to CAN channel is visible from the respective labeling (CAN channels CAN0 and CAN1).



Switch blocks for the CAN bus termination (industrial model)



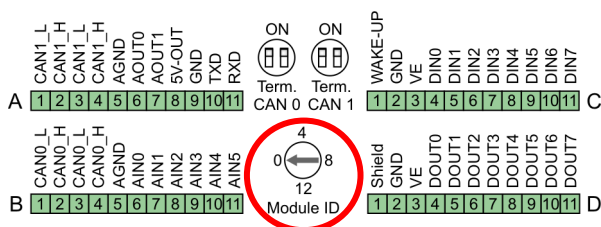
Switch blocks for the CAN bus termination (automotive model), rear side of the connector board when the PCAN-MIO housing is open

Type of transceiver	Termination at switch position*	
	OFF (standard)	ON
High-speed CAN (ISO 11898-2)	none	120 Ω between CAN_L and CAN_H
Low-speed CAN (ISO 11898-3)	4.7 k Ω for CAN_L and CAN_H	1.1 k Ω for CAN_L and CAN_H
Single-wire CAN (SAE J2411)	9.1 k Ω for CAN_SW	2.1 k Ω for CAN_SW

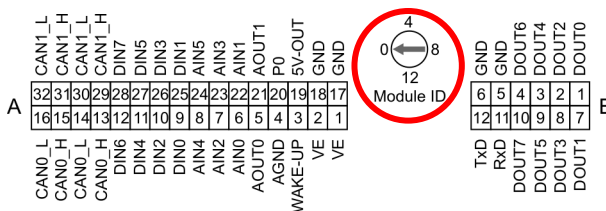
* Both switches of a switch block

4.3 Module ID (Rotary Switch)

The rotary switch has 16 rest positions to determine the module ID (0 - F hex = 0 - 15). The position for ID 0 is to the left. The model IDs increase in a clockwise direction.



Rotary switch for the module ID (industrial model)



Rotary switch for the module ID (automotive model),
remove cover plug if present

When the PCAN-MIO module is started the **configuration** with the number from the internal memory is loaded which matches the specified module ID (from ser. no. 100 excluding module ID 15). In addition, with the module ID there is a unique **identification** of the PCAN-MIO module during the PPCAN communication (configuration transfer). For the transmission of CAN messages in normal operation this module ID is not relevant.

From serial number 100 the **module ID 15** is reserved for the case of a firmware update failure so that there's still a possibility to access the PCAN-MIO module. At this setting a CAN bootloader is ready after a module reset. See also the separate documentation for a firmware update via CAN (on request).

▶ This is how you change the module ID of a PCAN-MIO module:

1. Change the position of the rotary switch with a small slot screwdriver.
2. Restart the module by briefly cutting off the power supply.

After the restart the changed module ID will be active.
Before the restart changes made at the rotary switch will have no influence on operation.



Tip: If the communication with the PCAN-MIO module is prevented because you do not know the bit rates used by the CAN channels, you can set the module ID to a position without configuration. In this case the respective standard bit rate is active for each equipped CAN transceiver (see following chapter 5 on page 27).

4.4 Status LED

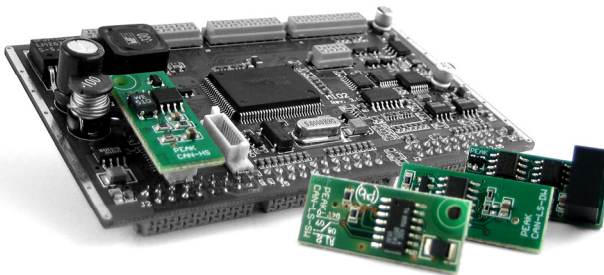
The status LED being located on the lower right of the front panel indicates the current operation status of the PCAN-MIO module by different colors and blinking frequencies.

Color	Blinking frequency	Operational status of the module
Red	Briefly on	Initialization of the module (power-on self test, POST)
	Permanently on	Hardware defect
Green	1 Hz (slow)	Normal operation with the configuration which is allocated to the currently specified module ID
	2 Hz (fast)	No or no valid configuration available for the currently specified module ID

5 Alternative CAN Transceiver Modules

The PCAN-MIO comes equipped with High-speed CAN transceivers (from ser. no. 100 with wake-up function). On request, we can provide each CAN channel also with an alternative CAN transceiver module.

The PCAN-MIO module automatically detects the CAN transceiver module in use and provides the according transmission parameters.



PCAN-MIO circuit board with plug-on transceiver modules

Following CAN transceiver modules are available for the PCAN-MIO:

Module Name	Item No.	Transmission Standard	Bitrates / Default Bitrate	Galv. isol.	Wake-up
PCAN-Transceiver TJA1041 ²	IPEH-001001	High-Speed-CAN ISO 11898-2	40 kbit/s to 1 Mbit/s / 500 kbit/s	no	yes
PCAN-Transceiver PCA82C251	IPEH-001002	High-Speed-CAN ISO 11898-2	5 kbit/s to 1 Mbit/s / 500 kbit/s	no	no
PCAN-Transceiver MAX3057-ISO ³	IPEH-001003	High-Speed-CAN ISO 11898-2	5 kbit/s to 1 Mbit/s / 500 kbit/s	yes	no
PCAN-Transceiver TH8056	IPEH-001004	Single-Wire-CAN SAE J2411	1,3 kbit/s to 40 kbit/s (Normal) or 100 kbit/s (High-Speed) / 33,3 kbit/s	no	yes
PCAN-Transceiver TJA1055	IPEH-001005	Low-Speed-CAN ISO 11898-3	20 kbit/s to 125 kbit/s / 125 kbit/s	no	yes
PCAN-Transceiver TJA1044-ISO	IPEH-001007	High-Speed-CAN ISO 11898-2	25 kbit/s to 1 Mbit/s / 500 kbit/s	yes	no

² Default equipment from ser. no. 100

³ During the startup process with this CAN transceiver module, errors may occur on the connected CAN bus. We recommend using the CAN transceiver module PCAN-Transceiver TJA1044-ISO alternatively.

6 Technical specifications

Power supply

Supply voltage	9 to 27 V DC
Brownout check	Reset if internal 5-Volt supply < 4.35 V
Current consumption	60 mA typ. (without separate circuits) 100 µA in power-down mode
Reverse-polarity protection	Yes
Sensor power supply	5 V (max. -2 %), 500 mA

Connector types

Spring terminal block 11-pin (for IPEH-002187)	Phoenix Contact FMC 1,5/11-ST-3,5 - 1952351
Automotive connector 12-pin (for IPEH-002187-A)	Housing: TE Connectivity 929051-1 Contacts carrier: TE Connectivity 968473-1 Crimp contacts: TE Connectivity 928999-1
Automotive connector 32-pin (for IPEH-002187-A)	Housing: TE Connectivity 929053-1 Contacts carrier: TE Connectivity 968265-1 Crimp contacts: TE Connectivity 928999-1

Digital outputs

Count	8, 2 of them PWM-capable (DOUT0 and DOUT1)
Voltage proof	DOUT2 - DOUT7: Low-side 30 V
Constant current	DOUT0 - DOUT1: High-side 1.4 A DOUT2 - DOUT7: High-/Low-side 0.6 A per output (1.4 A together)
Short-circuit current	DOUT0 - DOUT1: 5 A DOUT2 - DOUT7: 1 A
Range of frequency generation	DOUT0 - DOUT1: up to ser. no. 99: 65 to 6000 Hz from ser. no. 100: 17 to 6000 Hz

Analog outputs

Count	2
Voltage	0 to 10 V, each 20 mA (for internal reference voltage), other voltage range on request
Resolution	10 bit

Digital inputs

Count	8
Switching thresholds	ON ≥ 4 V, OFF ≤ 3 V
Frequency range DIN0 - DIN4	5 to 10,000 Hz
Integration time constant	23 μ s
Maximum input voltage	30 V

Analog inputs

Count	6
Measuring range	0 to 10 V, other measuring range on request
Resolution	10 bit
Sample rate	1 kHz
Input impedance	13.6 k Ω
Integration time constant	1.6 ms
Maximum input voltage	30 V

CAN

Standard transceiver	Up to ser. no. 99: High-speed CAN ISO 11898-2 (TJA1040) From ser. no. 100: High-speed CAN ISO 11898-2 with wake-up function (TJA1041)		
Other transceivers (on request)	High-speed CAN ISO 11898-2 (PCA82C251) without or with galvanic isolation Low-speed CAN ISO 11898-3 (TJA1055) with wake-up function Single-wire CAN SAE J2411 (TH8056) with wake-up function		
Wake-up time	typically 200 ms (depending on the size of the configuration)		
Termination	Setup with switches on the board		
	CAN	OFF	ON
	High-speed	none	120 Ω
	Low-speed	4.7 k Ω	1.1 k Ω
CAN ID reserved for configuration transfer	Single-wire	9.1 k Ω	2.1 k Ω
	7E7h		

Interference resistance

Tests	IEC 61000 and DIN EN 61326 compliant
Peculiarity surge	±500 V

Environment

Operating temperature	-40 to +85 °C (-40 - +185 °F)
Temperature for storage and transport	-40 to +100 °C (-40 - +212 °F)
Relative humidity	15 to 90 %, not condensing
Ingress protection (IEC 60529)	IP20

Measures

Size	130 x 65 x 35 mm (without connectors) See also dimension drawings in Appendix B on page 34
Weight	max. 280 g

Conformity

RoHS	EU Directive 2011/65/EU + 2015/863/EU DIN EN IEC 63000:2019-05
EMC	EU Directive 2014/30/EU DIN EN IEC 61326-1:2022-11

Appendix A Conformity

A.1 CE

EU Declaration of Conformity



This declaration applies to the following product:

Product name: **PCAN-MIO**
Item number(s): **IPEH-002187, IPEH-002187-A**
Manufacturer: **PEAK-System Technik GmbH**
Otto-Röhm-Straße 69
64293 Darmstadt
Germany



We declare under our sole responsibility that the mentioned product is in conformity with the following directives and the affiliated harmonized standards:

EU Directive 2011/65/EU (RoHS 2) + 2015/863/EU (amended list of restricted substances)

DIN EN IEC 63000:2019-05

Technical documentation for the assessment of electrical and electronic products with respect to the restriction of hazardous substances (IEC 63000:2016);
German version of EN IEC 63000:2018

EU Directive 2014/30/EU (Electromagnetic Compatibility)

DIN EN 61326-1:2022-11

Electrical equipment for measurement, control and laboratory use - EMC requirements - Part 1:
General requirements (IEC 61326-1:2020);
German version of EN IEC 61326-1:2021

Darmstadt, 19 January 2023

A handwritten signature in black ink, appearing to read "Uwe Wilhelm".

Uwe Wilhelm, Managing Director

A.2 UKCA

UK Declaration of Conformity



This declaration applies to the following product:

Product name: **PCAN-MIO**
Item number(s): **IPEH-002187, IPEH-002187-A**

Manufacturer:

PEAK-System Technik GmbH
Otto-Röhm-Straße 69
64293 Darmstadt
Germany

UK authorized representative:

Control Technologies UK Ltd
Unit 1, Stoke Mill,
Mill Road, Sharnbrook,
Bedfordshire, MK44 1NN, UK



We declare under our sole responsibility that the mentioned product is in conformity with the following UK legislations and the affiliated harmonized standards:

The Restriction of the Use of Certain Hazardous Substances in Electrical and Electronic Equipment Regulations 2012

DIN EN IEC 63000:2019-05

Technical documentation for the assessment of electrical and electronic products with respect to the restriction of hazardous substances (IEC 63000:2016);
German version of EN IEC 63000:2018

Electromagnetic Compatibility Regulations 2016

DIN EN 61326-1:2022-11

Electrical equipment for measurement, control and laboratory use - EMC requirements - Part 1: General requirements (IEC 61326-1:2020);
German version of EN IEC 61326-1:2021

Darmstadt, 19 January 2023

A handwritten signature in black ink, appearing to read "Uwe Wilhelm".

Uwe Wilhelm, Managing Director

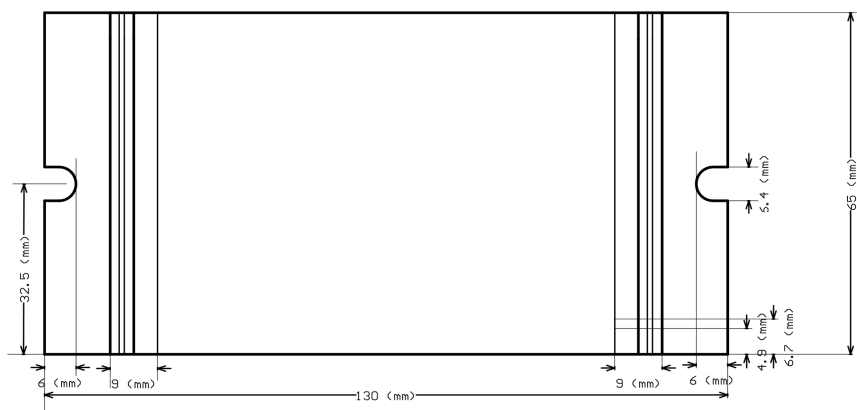
Technical drawing of a rectangular plate with dimensions and hole locations. The plate has a width of 105 mm and a height of 147 mm. The drawing shows two rows of holes, each with 10 holes. The holes are arranged in two rows, each with 10 holes. The dimensions are as follows:

- Overall width: 105 mm
- Overall height: 147 mm
- Distance from top edge to first row of holes: 33.8 mm
- Distance between rows of holes: 30.3 mm
- Distance from bottom edge to second row of holes: 23.8 mm
- Distance from left edge to first hole in first row: 11.3 mm
- Distance between holes in first row: 9.4 mm
- Distance from left edge to first hole in second row: 11.3 mm
- Distance between holes in second row: 9.4 mm
- Distance from right edge to last hole in first row: 14.7 mm
- Distance from right edge to last hole in second row: 14.7 mm
- Distance from top edge to center of first hole in first row: 39.3 mm
- Distance from top edge to center of first hole in second row: 59 mm
- Distance from top edge to center of first hole in third row: 65 mm
- Distance from top edge to center of first hole in fourth row: 55.8 mm
- Distance from top edge to center of first hole in fifth row: 52.5 mm
- Distance from top edge to center of first hole in sixth row: 49.2 mm
- Distance from top edge to center of first hole in seventh row: 46.1 mm
- Distance from top edge to center of first hole in eighth row: 39.3 mm
- Distance from top edge to center of first hole in ninth row: 33.8 mm
- Distance from top edge to center of first hole in tenth row: 23.8 mm
- Distance from top edge to center of first hole in eleventh row: 14.7 mm
- Distance from top edge to center of first hole in twelfth row: 11.3 mm
- Distance from top edge to center of first hole in thirteenth row: 9.4 mm
- Distance from top edge to center of first hole in fourteenth row: 11.3 mm
- Distance from top edge to center of first hole in fifteenth row: 14.7 mm
- Distance from top edge to center of first hole in sixteenth row: 23.8 mm
- Distance from top edge to center of first hole in seventeenth row: 33.8 mm
- Distance from top edge to center of first hole in eighteenth row: 39.3 mm
- Distance from top edge to center of first hole in nineteenth row: 59 mm
- Distance from top edge to center of first hole in twentieth row: 65 mm
- Distance from top edge to center of first hole in twenty-first row: 55.8 mm
- Distance from top edge to center of first hole in twenty-second row: 52.5 mm
- Distance from top edge to center of first hole in twenty-third row: 49.2 mm
- Distance from top edge to center of first hole in twenty-fourth row: 46.1 mm
- Distance from top edge to center of first hole in twenty-fifth row: 39.3 mm
- Distance from top edge to center of first hole in twenty-sixth row: 33.8 mm
- Distance from top edge to center of first hole in twenty-seventh row: 23.8 mm
- Distance from top edge to center of first hole in twenty-eighth row: 14.7 mm
- Distance from top edge to center of first hole in twenty-ninth row: 11.3 mm
- Distance from top edge to center of first hole in thirtieth row: 9.4 mm
- Distance from top edge to center of first hole in thirty-first row: 11.3 mm
- Distance from top edge to center of first hole in thirty-second row: 14.7 mm
- Distance from top edge to center of first hole in thirty-third row: 23.8 mm
- Distance from top edge to center of first hole in thirty-fourth row: 33.8 mm
- Distance from top edge to center of first hole in thirty-fifth row: 39.3 mm
- Distance from top edge to center of first hole in thirty-sixth row: 59 mm
- Distance from top edge to center of first hole in thirty-seventh row: 65 mm
- Distance from top edge to center of first hole in thirty-eighth row: 55.8 mm
- Distance from top edge to center of first hole in thirty-ninth row: 52.5 mm
- Distance from top edge to center of first hole in fortieth row: 49.2 mm
- Distance from top edge to center of first hole in forty-first row: 46.1 mm
- Distance from top edge to center of first hole in forty-second row: 39.3 mm
- Distance from top edge to center of first hole in forty-third row: 33.8 mm
- Distance from top edge to center of first hole in forty-fourth row: 23.8 mm
- Distance from top edge to center of first hole in forty-fifth row: 14.7 mm
- Distance from top edge to center of first hole in forty-sixth row: 11.3 mm
- Distance from top edge to center of first hole in forty-seventh row: 9.4 mm
- Distance from top edge to center of first hole in forty-eighth row: 11.3 mm
- Distance from top edge to center of first hole in forty-ninth row: 14.7 mm
- Distance from top edge to center of first hole in fiftieth row: 23.8 mm
- Distance from top edge to center of first hole in fifty-first row: 33.8 mm
- Distance from top edge to center of first hole in fifty-second row: 39.3 mm
- Distance from top edge to center of first hole in fifty-third row: 59 mm
- Distance from top edge to center of first hole in fifty-fourth row: 65 mm
- Distance from top edge to center of first hole in fifty-fifth row: 55.8 mm
- Distance from top edge to center of first hole in fifty-sixth row: 52.5 mm
- Distance from top edge to center of first hole in fifty-seventh row: 49.2 mm
- Distance from top edge to center of first hole in fifty-eighth row: 46.1 mm
- Distance from top edge to center of first hole in fifty-ninth row: 39.3 mm
- Distance from top edge to center of first hole in sixtieth row: 33.8 mm
- Distance from top edge to center of first hole in sixty-first row: 23.8 mm
- Distance from top edge to center of first hole in sixty-second row: 14.7 mm
- Distance from top edge to center of first hole in sixty-third row: 11.3 mm
- Distance from top edge to center of first hole in sixty-fourth row: 9.4 mm
- Distance from top edge to center of first hole in sixty-fifth row: 11.3 mm
- Distance from top edge to center of first hole in sixty-sixth row: 14.7 mm
- Distance from top edge to center of first hole in sixty-seventh row: 23.8 mm
- Distance from top edge to center of first hole in sixty-eighth row: 33.8 mm
- Distance from top edge to center of first hole in sixty-ninth row: 39.3 mm
- Distance from top edge to center of first hole in seventieth row: 59 mm
- Distance from top edge to center of first hole in seventy-first row: 65 mm
- Distance from top edge to center of first hole in seventy-second row: 55.8 mm
- Distance from top edge to center of first hole in seventy-third row: 52.5 mm
- Distance from top edge to center of first hole in seventy-fourth row: 49.2 mm
- Distance from top edge to center of first hole in seventy-fifth row: 46.1 mm
- Distance from top edge to center of first hole in seventy-sixth row: 39.3 mm
- Distance from top edge to center of first hole in seventy-seventh row: 33.8 mm
- Distance from top edge to center of first hole in seventy-eighth row: 23.8 mm
- Distance from top edge to center of first hole in seventy-ninth row: 14.7 mm
- Distance from top edge to center of first hole in eightieth row: 11.3 mm
- Distance from top edge to center of first hole in eighty-first row: 9.4 mm
- Distance from top edge to center of first hole in eighty-second row: 11.3 mm
- Distance from top edge to center of first hole in eighty-third row: 14.7 mm
- Distance from top edge to center of first hole in eighty-fourth row: 23.8 mm
- Distance from top edge to center of first hole in eighty-fifth row: 33.8 mm
- Distance from top edge to center of first hole in eighty-sixth row: 39.3 mm
- Distance from top edge to center of first hole in eighty-seventh row: 59 mm
- Distance from top edge to center of first hole in eighty-eighth row: 65 mm
- Distance from top edge to center of first hole in eighty-ninth row: 55.8 mm
- Distance from top edge to center of first hole in ninetieth row: 52.5 mm
- Distance from top edge to center of first hole in ninety-first row: 49.2 mm
- Distance from top edge to center of first hole in ninety-second row: 46.1 mm
- Distance from top edge to center of first hole in ninety-third row: 39.3 mm
- Distance from top edge to center of first hole in ninety-fourth row: 33.8 mm
- Distance from top edge to center of first hole in ninety-fifth row: 23.8 mm
- Distance from top edge to center of first hole in ninety-sixth row: 14.7 mm
- Distance from top edge to center of first hole in ninety-seventh row: 11.3 mm
- Distance from top edge to center of first hole in ninety-eighth row: 9.4 mm
- Distance from top edge to center of first hole in ninety-ninth row: 11.3 mm
- Distance from top edge to center of first hole in one hundredth row: 14.7 mm
- Distance from top edge to center of first hole in one hundred and first row: 23.8 mm
- Distance from top edge to center of first hole in one hundred and second row: 33.8 mm
- Distance from top edge to center of first hole in one hundred and third row: 39.3 mm
- Distance from top edge to center of first hole in one hundred and fourth row: 59 mm
- Distance from top edge to center of first hole in one hundred and fifth row: 65 mm
- Distance from top edge to center of first hole in one hundred and sixth row: 55.8 mm
- Distance from top edge to center of first hole in one hundred and seventh row: 52.5 mm
- Distance from top edge to center of first hole in one hundred and eighth row: 49.2 mm
- Distance from top edge to center of first hole in one hundred and ninth row: 46.1 mm
- Distance from top edge to center of first hole in one hundred and tenth row: 39.3 mm
- Distance from top edge to center of first hole in one hundred and eleventh row: 33.8 mm
- Distance from top edge to center of first hole in one hundred and twelfth row: 23.8 mm
- Distance from top edge to center of first hole in one hundred and thirteenth row: 14.7 mm
- Distance from top edge to center of first hole in one hundred and fourteenth row: 11.3 mm
- Distance from top edge to center of first hole in one hundred and fifteenth row: 9.4 mm
- Distance from top edge to center of first hole in one hundred and sixteenth row: 11.3 mm
- Distance from top edge to center of first hole in one hundred and seventeenth row: 14.7 mm
- Distance from top edge to center of first hole in one hundred and eighteenth row: 23.8 mm
- Distance from top edge to center of first hole in one hundred and nineteenth row: 33.8 mm
- Distance from top edge to center of first hole in one hundred and twentieth row: 39.3 mm
- Distance from top edge to center of first hole in one hundred and twenty-first row: 59 mm
- Distance from top edge to center of first hole in one hundred and twenty-second row: 65 mm
- Distance from top edge to center of first hole in one hundred and twenty-third row: 55.8 mm
- Distance from top edge to center of first hole in one hundred and twenty-fourth row: 52.5 mm
- Distance from top edge to center of first hole in one hundred and twenty-fifth row: 49.2 mm
- Distance from top edge to center of first hole in one hundred and twenty-sixth row: 46.1 mm
- Distance from top edge to center of first hole in one hundred and twenty-seventh row: 39.3 mm
- Distance from top edge to center of first hole in one hundred and twenty-eighth row: 33.8 mm
- Distance from top edge to center of first hole in one hundred and twenty-ninth row: 23.8 mm
- Distance from top edge to center of first hole in one hundred and thirtieth row: 14.7 mm
- Distance from top edge to center of first hole in one hundred and thirty-first row: 11.3 mm
- Distance from top edge to center of first hole in one hundred and thirty-second row: 9.4 mm
- Distance from top edge to center of first hole in one hundred and thirty-third row: 11.3 mm
- Distance from top edge to center of first hole in one hundred and thirty-fourth row: 14.7 mm
- Distance from top edge to center of first hole in one hundred and thirty-fifth row: 23.8 mm
- Distance from top edge to center of first hole in one hundred and thirty-sixth row: 33.8 mm
- Distance from top edge to center of first hole in one hundred and thirty-seventh row: 39.3 mm
- Distance from top edge to center of first hole in one hundred and thirty-eighth row: 59 mm
- Distance from top edge to center of first hole in one hundred and thirty-ninth row: 65 mm
- Distance from top edge to center of first hole in one hundred and fortieth row: 55.8 mm
- Distance from top edge to center of first hole in one hundred and forty-first row: 5

Technical drawing of the front view of a rectangular metal plate. The drawing includes the following dimensions and features:

- Overall Dimensions:**
 - Width: 105 (mm)
 - Height: 39.9 (mm)
- Internal Dimensions and Spacing:**
 - Distance from top edge to first horizontal line: 39 (mm)
 - Distance between first and second horizontal lines: 70 (mm)
 - Distance between second and third horizontal lines: 65 (mm)
 - Distance between third and fourth horizontal lines: 63.3 (mm)
 - Distance from bottom edge to fourth horizontal line: 56.6 (mm)
- Vertical Dimensions (Left Side):**
 - Distance from top edge to first vertical line: 33.8 (mm)
 - Distance from first vertical line to second vertical line: 30.3 (mm)
 - Distance from second vertical line to third vertical line: 26.8 (mm)
 - Distance from third vertical line to fourth vertical line: 10.7 (mm)
 - Distance from fourth vertical line to bottom edge: 1.7 (mm)
- Vertical Dimensions (Right Side):**
 - Distance from top edge to first vertical line: 24.5 (mm)
 - Distance from first vertical line to second vertical line: 8.4 (mm)
- Features:**
 - Four circular holes, one in each corner, with a diameter of $\varnothing 10$.
 - A central circular hole with a diameter of $\varnothing 10$.
 - A small circular hole with a diameter of $\varnothing 2.8$ located near the bottom center.

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Top view of the bottom plate

The figures do not show the original size.

Appendix C Disposal

The PCAN-MIO must not be disposed of in household waste. Dispose of the PCAN-MIO properly in accordance with local regulations.

Appendix D Module Resources

The table lists all the logical resources of the PCAN-MIO module, arranged by I/O functions (column “I/O Function”) and the respective I/O numbers (column “I/O Number”).

I/O Function	I/O Number	Possible values	Connection	Function
DOut Level (00h)				
	DO H0	0: open, 1: High	D4	High-side output 0
	DO H1		D5	High-side output 1
	DO H2		D6	High-side output 2
	DO H3		D7	High-side output 3
	DO H4		D8	High-side output 4
	DO H5		D9	High-side output 5
	DO H6		D10	High-side output 6
	DO H7		D11	High-side output 7
	DO HL2	0: Low, 1: High	D6	Push-pull output 2
	DO HL3		D7	Push-pull output 3
	DO HL4		D8	Push-pull output 4
	DO HL5		D9	Push-pull output 5
	DO HL6		D10	Push-pull output 6
	DO HL7		D11	Push-pull output 7
	DO L2	0: open, 1: Low	D6	Low-side output 2
	DO L3		D7	Low-side output 3
	DO L4		D8	Low-side output 4
	DO L5		D9	Low-side output 5
	DO L6		D10	Low-side output 6
	DO L7		D11	Low-side output 7
DOut Frequency (01h)				
	Freq 0	Up to ser. no. 99: 65 to 6000	D4	Frequency output 0
	Freq 1	From ser. no. 100: 17 to 6000	D5	Frequency output 1

I/O Function	I/O Number	Possible values	Connection	Function		
DOut Ratio (03h)						
	PWM 0	0 to 255 (255 = 100 %)	D4	PWM output 0	Generates a PWM signal with variable duty cycle and configurable frequency	
	PWM 1		D5	PWM output 1		
AOut Level (10h)						
	AOut 0	0 to 1023 (1023 = 10 V)	A6	Analog output 0	10-bit D/A converter, I _a = 20 mA	
	AOut 1		A7	Analog output 1		
Special Out (70h)						
	Supply 5V	0: Off, 1: On	A8	5-Volt supply for external sensor I _a = 500 mA		
	Selfhold	0: Off, 1: On		1 at power-on. To switch off the module set to 0.		
	RS-232	0: Off, 1: On		1 at power-on. Switches the High stage for the pull-ups at the digital inputs, the reference voltage for analog in-/outputs, the RS-232 level converter.		
	LED Pattern			(Reserved)		
	CAN 0 Mode	0 to 5	CAN_L: B1, B3 CAN_H: B2, B4 SW-CAN: B2, B4	Operation mode CAN transceiver 0	0: Normal (all transceivers) 1: WakeUp (TH8056) 2: PowerDown (PCA82C251, MAX3057-ISO, TH8056, TJA1055, TJA1044-ISO) 3: ListenOnly (TJA1041, PCA82C251, TJA1055, TJA1044-ISO) 4: HighSpeed (TH8056) 5: Standby (TJA1041, PCA82C251, TJA1055)	
	CAN 1 Mode		CAN-L: A1, A3 CAN-H: A2, A4 SW-CAN: A2, A4	Operation mode CAN transceiver 1		
	Routing 0 to 1 All	0: Off 1: only 11-bit IDs 2: only 29-bit IDs 3: 11-bit and 29-bit IDs		Forwarding of all CAN messages	from bus 0 to bus 1	Not to be combined with Explicit or Excluding
	Routing 1 to 0 All				from bus 1 to bus 0	
	Debug Mode			(Reserved)		
	Routing 0 to 1 Explicit	11-bit CAN ID		Forward the specified 11-bit CAN ID	from bus 0 to bus 1	Not to be combined with All or Excluding
	Routing 1 to 0 Explicit				from bus 1 to bus 0	
	Routing 0 to 1 Excluding	11-bit CAN ID		Forwarding of all CAN messages except the specified 11-bit CAN ID	from bus 0 to bus 1	Not to be combined with All or Explicit
	Routing 1 to 0 Excluding				from bus 1 to bus 0	
	CAN 0 Bitrate Raw	0x0000 to 0xFFFF		Set the CAN bit rate by direct insertion of the register value into the bit rate register		
	CAN 1 Bitrate Raw					
	CAN Bitrate: 33.3 kbit/s	0, 1 (CAN channel)		Specify a CAN bit rate		
	CAN Bitrate: 47.6 kbit/s					
	CAN Bitrate: 50 kbit/s					

I/O Function	I/O Number	Possible values	Connection	Function	
	CAN Bitrate: 83.3 kbit/s				
	CAN Bitrate: 95.2 kbit/s				
	CAN Bitrate: 100 kbit/s				
	CAN Bitrate: 125 kbit/s				
	CAN Bitrate: 250 kbit/s				
	CAN Bitrate: 500 kbit/s				
	CAN Bitrate: 1 Mbit/s				
DIn Level (80h)					
	Level 0	0: Low 1: High	C4	Digital input 0	Vih = 4 V Vil = 3 V
	Level 1		C5	Digital input 1	
	Level 2		C6	Digital input 2	
	Level 3		C7	Digital input 3	
	Level 4		C8	Digital input 4	
	Level 5		C9	Digital input 5	
	Level 6		C10	Digital input 6	
	Level 7		C11	Digital input 7	
DIn Frequency (81h)					
	Freq 0	5 to 10000 (Hz)	C4	Frequency input 0	Frequency measurement Vih = 4 V Vil = 3 V
	Freq 1		C5	Frequency input 1	
	Freq 2		C6	Frequency input 2	
	Freq 3		C7	Frequency input 3	
	Freq 4		C8	Frequency input 4	
DIn Ratio (83h)					
	Ratio 0	0 to 1000 (1000 = 100 % High)	C4	PWM input 0	Measurement of the duty cycle (high phase) Vih = 4 V Vil = 3 V (only to 1 kHz)
	Ratio 1		C5	PWM input 1	
	Ratio 2		C6	PWM input 2	
	Ratio 3		C7	PWM input 3	
	Ratio 4		C8	PWM input 4	

I/O Function	I/O Number	Possible values	Connection	Function
DIn Low Frequency (86h)				
	Low Freq 0	1 to 50000 (0.001 Hz)	C4	Digital input 0
	Low Freq 1		C5	Digital input 1
	Low Freq 2		C6	Digital input 2
	Low Freq 3		C7	Digital input 3
	Low Freq 4		C8	Digital input 4
Measurement of low frequencies (0.001 - 50 Hz) Vih = 4 V Vil = 3 V Sampling each second, calculation each 10 milliseconds				
DIn Duty Cycle (87h)				
	Duty Cycle 0	1 to 1000 (%)	C4	Digital input 0
	Duty Cycle 1		C5	Digital input 1
	Duty Cycle 2		C6	Digital input 2
	Duty Cycle 3		C7	Digital input 3
	Duty Cycle 4		C8	Digital input 4
Measurement of the duty cycle (0 to 1000 %) at frequencies from 0.001 to 50 Hz Vih = 4 V Vil = 3 V Sampling each second, calculation each 10 milliseconds				
Pull-Up/Down (88h)				
	Pull-Up 0; 1-3; 4; 5-7	0: deactivated 1: activated	C4 ... C11	Pull-up resistor for digital input or digital input group
	Pull-Dn 0; 1-3; 4; 5-7			Pull-down resistor for digital input or digital input group
Pull-up/pull-down resistors each 4.7 kΩ. This I/O function is only available in the hardware profile “PCAN-MIO (32-Bit)” (from ser. no. 100).				
AIn Level (90h)				
	AIN 0	0 to 1023	B6	Analog input 0
	AIN 1		B7	Analog input 1
	AIN 2		B8	Analog input 2
	AIN 3		B9	Analog input 3
	AIN 4		B10	Analog input 4
	AIN 5		B11	Analog input 5
Input range: 0 - 10 V Hardware low-pass: 6.8 kΩ, 33 nF				
Tau (98h)				
	Tau 0	0 to 60000 (ms)		Time constant for analog input 0
	Tau 1			Time constant for analog input 1
	Tau 2			Time constant for analog input 2
	Tau 3			Time constant for analog input 3
	Tau 4			Time constant for analog input 4
	Tau 5			Time constant for analog input 5
Software low-pass for analog inputs				

I/O Function	I/O Number	Possible values	Connection	Function
Const (CCh)				
	(See list in the PPCAN-Editor)	(Diverse values)		Diverse constants Read only; can be used as input constants.
Positive Const (CDh)				
	0 to 255	(0 to +255)		Positive constants Read only; can be used as input constants.
Negative Const (CEh)				
	0 to -255	(0 to -255)		Negative constants Read only; can be used as input constants.
Special In (F0h)				
	Conf Ver Main	0 to 255		Main version number of the configuration Version of the configuration; can be specified in the PPCAN-Editor during the module-specific settings
	Conf Ver Sub	0 to 255		Secondary version number of the configuration
	FW Ver Main	0 to 7		Main version number of the firmware
	FW Ver Sub	0 to 31		Secondary version number of the firmware For information purposes; read only
	FW Build	0 to 255		Build version number of the firmware
	Module ID	0 to 15		Module ID Position of the corresponding rotary switch on the PCAN-MIO module; ID must be unique within the CAN net.
	Main Cycle Counter	0 to 65535		Count of computation cycles of the firmware since the last call; read only
	Main Cycle Time Max			Maximum duration in ms for a computation cycle since the last call; read only
	Main Cycle Time Avg			Average duration in µs for a computation cycle since the last call; read only
	none			No function Can be used as place-holder if the corresponding input or output has no function.
32bit Variable (FFh)				
	0 to 255	32 Bit signed		Internal 32-bit variable Temporary memory for values of function blocks and CAN variables