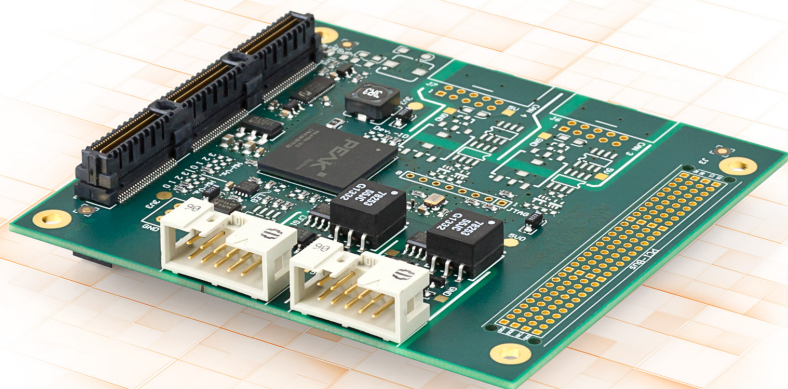


PCAN-PCI/104-Express

User Manual



Relevant Products

Product name	Model	Part number
PCAN-PCI/104-Express Single Channel	One CAN channel	IPEH-003054
PCAN-PCI/104-Express Single Channel opto-decoupled	One CAN channel, galvanic isolation for CAN connection	IPEH-003056
PCAN-PCI/104-Express Dual Channel	Two CAN channels	IPEH-003055
PCAN-PCI/104-Express Dual Channel opto-decoupled	Two CAN channels, galvanic isolation for CAN connection	IPEH-003057
PCAN-PCI/104-Express Quad Channel opto-decoupled	Four CAN channels, galvanic isolation for CAN connection	IPEH-003058

The cover picture shows the product PCAN-PCI/104-Express Dual Channel opto-decoupled. Other product versions have an identical form factor but vary in equipment.

Imprint

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PEAK-System Technik GmbH
Otto-Röhm-Straße 69
64293 Darmstadt
Germany

Phone: +49 6151 8173-20
Fax: +49 6151 8173-29

www.peak-system.com
info@peak-system.com

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Contents

Imprint	2
Relevant Products	2
Contents	3
1 Introduction	5
1.1 Properties at a Glance	6
1.2 System Requirements	6
1.3 Scope of Supply	7
2 Configuration	8
2.1 Voltage Supply of External Devices	8
3 Installation	11
3.1 Install Device Driver Setup	11
3.2 Install CAN interface	11
3.3 Check Operational Readiness	12
4 Connecting the CAN Bus	13
4.1 Connection over D-Sub Connector	13
4.2 Cabling	13
4.3 Example Application under Windows	14
5 CAN Monitor PCAN-View	15
5.1 Initialize CAN interface	16
5.2 Transmit CAN message	18
5.3 Additional Tabs	19
6 API PCAN-Basic	24
6.1 Features of PCAN-Basic	25
6.2 Principle Description of the API	26

7 Technical Data 27

Appendix A CE Certificate 29

Appendix B UKCA Certificate 30

Appendix C Dimension Drawings 31

Appendix D Quick Reference 32

Appendix E Linux 33

Appendix F Disposal 34

1 Introduction

The PCAN-PCI/104-Express card enables the connection of one, two, or four CAN buses to a PCI/104-Express system. Up to four cards can be stacked together. The CAN bus is connected using a 9-pin D-Sub plug on the slot brackets supplied. There is galvanic isolation of up to 500 Volts between the computer and CAN sides. There are versions with one, two and four channels.

The package is also supplied with the CAN monitor PCAN-View for Windows and the programming interface PCAN-Basic.



This manual describes the use of the CAN interface with **Windows**.
Device drivers and application information for **Linux**:
www.peak-system.com/quick/DL-Driver-E



At the end of this manual you can find a Quick Reference with brief information about the installation and operation of the CAN interface.

1.1 Properties at a Glance

- PCI/104-Express card, 1 lane (x1)
- Form factor PC/104
- Up to four cards can be used in one system
- 1, 2 or 4 High-speed CAN channels (ISO 11898-2)
- Bit rates from 5 kbit/s up to 1 Mbit/s
- Compliant with CAN specifications 2.0A (11-bit ID) and 2.0B (29-bit ID)
- Connection to CAN bus through D-Sub slot brackets, 9-pin (in accordance with CiA® 106)
- FPGA implementation of the CAN controller (SJA1000 compatible)
- NXP PCA82C251 CAN transceiver
- Galvanic isolation on the CAN connection up to 500 V, separate for each CAN channel
- Supplied only via the 5 V line
- 5-Volt supply to the CAN connection can be connected through a solder jumper, e.g. for external bus converter
- Extended operating temperature range from -40 to +85 °C (-40 to +185 °F)
- Optional available: PC/104 stack-through connector

1.2 System Requirements

PC/104 stack with

- PCIe/104 connectivity to the host
- Operating system Windows 11 (x64), 10 (x64), or Linux

1.3 Scope of Supply

- PCAN-PCI/104-Express card
- Slot bracket with D-Sub connector(s) for the CAN bus
(two for the four-channel version)

Downloads

- Device drivers for Windows 11 (x64), 10 (x64), and Linux
- CAN monitor PCAN-View for Windows
- Programming interface PCAN-Basic for developing applications with CAN connection
- Programming interfaces for standardized protocols from the automotive sector
- Manual in PDF format

2 Configuration

Before installing the CAN interface into a PC/104 stack:

Check if you need the following configuration.

2.1 Voltage Supply of External Devices



Attention! The voltage supply for external devices is not protected separately. Therefore, turn off the computer before you connect and disconnect CAN cables or peripheral systems.

Optionally, an external voltage supply can be connected separately for each CAN channel via solder bridges at pin 9 on the D-Sub connector. This allows external devices to be supplied with a voltage of 5 V DC, for example bus converters (PCAN-TJA1054 for Low-Speed-CAN). Pin 9 is not connected at delivery.

The current output is limited to

- 100 mA without galvanic isolation.
- 50 mA with galvanic isolation.

The lower current output of the versions with galvanic isolation is due to an intermediate DC/DC converter.

2.1.1 Activate voltage supply



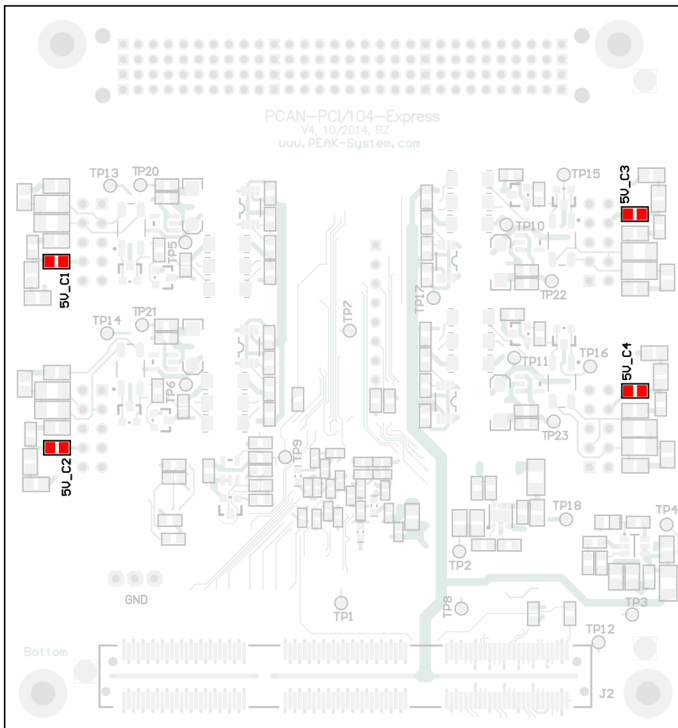
Risk of short circuit! Soldering on the CAN interface may only be performed by qualified electrical engineering personnel.











Attention! Electrostatic discharge (ESD) can damage or destroy components on the card. Take precautions to avoid ESD.

The solder fields for the power supply of external devices are located on the bottom side of the bottom side of the CAN interface. The following picture shows the solder field positions on the fourchannel card. The solder fields for the single and dual channel versions are located in the same positions.

Set the solder bridge(s) on the card according to the desired settings.



5-Volt supply via D-Sub plug			
D-Sub connector	Solder field	Without (Standard)	Pin 9
CAN 1	5V_C1		
CAN 2	5V_C2		
CAN 3	5V_C3		
CAN 4	5V_C4		

3 Installation

This chapter covers the software setup for the CAN interface PCAN-PCI/104-Express under Windows and the installation of the CAN interface into the PC/104 stack.

Note: For installation on Linux, see Appendix E *Linux*.

Install the driver before you install the CAN interface.

3.1 Install Device Driver Setup

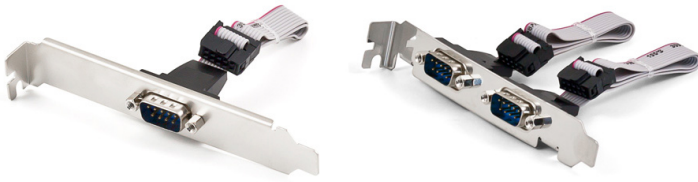
1. Download the device driver setup from our website:
www.peak-system.com/quick/DL-Driver-E
2. Unpack the file `PEAK-System_Driver-Setup.zip`
3. Double-click the file `PeakOemDrv.exe`
The driver setup starts.
4. Follow the program instructions.

3.2 Install CAN interface



Attention! Electrostatic discharge (ESD) can damage or destroy components on the card. Take precautions to avoid ESD.

1. Connect one cable per CAN connection from the slot bracket to a 10-pin socket on the CAN interface.



2. Shut down the computer.
3. Disconnect the computer's power supply.
4. Plug the CAN interface directly onto the host or onto another PCI/104 Express card of the PC/104 stack.

A maximum of four PCI/104-Express cards per PC/104 system is possible, either all on top or all beneath the host.

5. Install the slot bracket.
6. Reconnect the computer power supply.
7. Turn on the computer and start Windows.

Windows detects the new hardware and completes the driver installation.

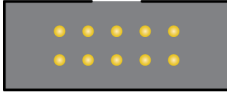

3.3 Check Operational Readiness

1. Open the Windows Start menu.
2. Type `Peak Settings` and press `Enter`.
The window *PEAK Settings* appears.
3. Select *CAN Hardware*.
The connected CAN interface is displayed.

4 Connecting the CAN Bus

4.1 Connection over D-Sub Connector

After the slot bracket has been connected to the CAN interface a CAN bus can be connected to the D-Sub connector. The pin assignment of the D-Sub connector corresponds to the specification CiA® 106:

10-pin connector on CAN interface	D-Sub plug on slot bracket, 9-pin	Assignment
9 7 5 3 1  10 8 6 4 2	1 2 3 4 5  6 7 8 9	
2	6	GND
3	2	CAN_Low
4	7	CAN_High
5	3	GND
8	9	+5 V (optional)
1, 6, 7, 9, 10	1, 4, 5, 8	None

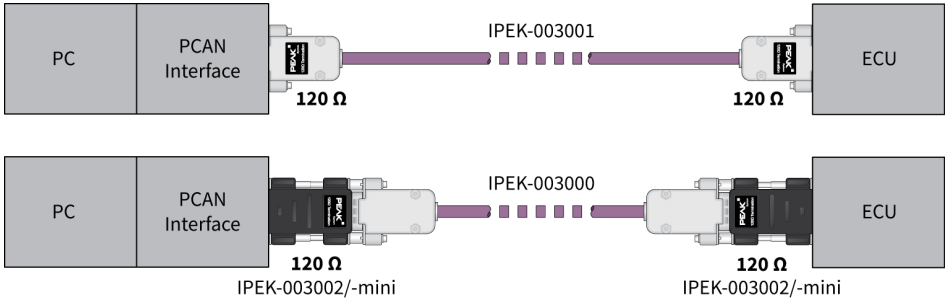
4.2 Cabling

4.2.1 Termination

The High-speed CAN bus (ISO 11898-2) must be terminated with 120 Ω on both ends. The termination prevents interfering signal reflections and ensures the proper operation of the transceivers of the connected CAN nodes (CAN interfaces, control devices).

The CAN interface PCAN-PCI/104-Express does not have an internal termination. Use the CAN interface on a terminated CAN bus.

4.2.2 Example of a Connection



This example shows a connection between the PCAN Interface and a control unit (ECU). The upper example shows a connection with a cable which is terminated with 120 Ω at both ends. At the lower example the connection is made with termination adapters.

4.2.3 Maximum Bus Length

The maximum bus length depends primarily on the bit rate:

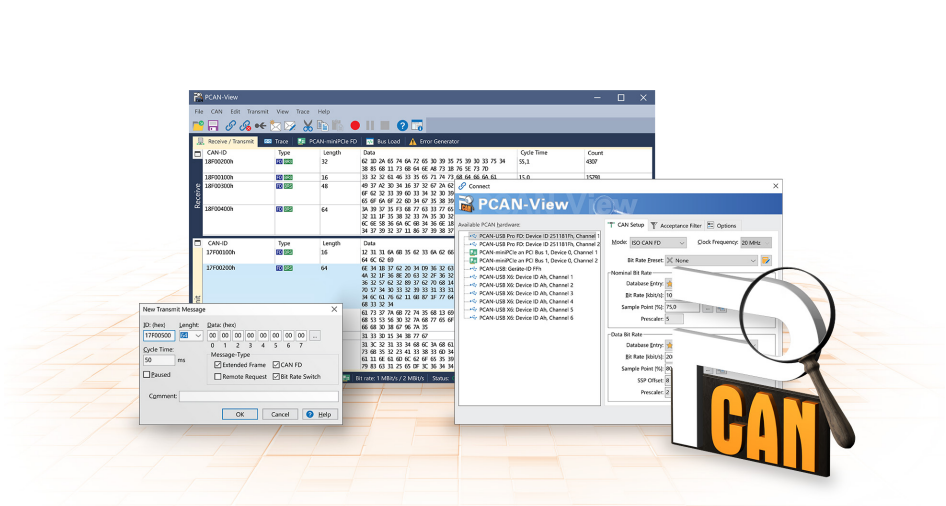
Nominal bit rate	Buslength
1 Mbit/s	40 m
500 kbit/s	110 m
250 kbit/s	240 m
125 kbit/s	500 m
50 kbit/s	1.3 km
20 kbit/s	3.3 km
10 kbit/s	6.6 km
5 kbit/s	13 km

The listed values have been calculated on the basis of an idealized system and can differ from reality.

4.3 Example Application under Windows

As an example application for accessing the CAN interface, run the CAN monitor PCAN-View from the Windows Start menu.

5 CAN Monitor PCAN-View



The CAN monitor PCAN-View is a Windows software for viewing, sending, and recording CAN and CAN FD messages. The software is installed with the installation of the device driver package under Windows.

In the following the initialization of a CAN interface is described as an example.

Detailed information about using PCAN-View can be found in the program window under the menu item *Help*.

5.1 Initialize CAN interface

1. Open the program *PCAN-View* via the Windows Start menu.
- Depending on the CAN interface the *Connect* dialog is displayed with or without settings for CAN FD.

CAN

BTR 0	BTR 1	Sample Point	Tq	Nq	SJW
00h	05h	88 %	125 ns	8	1
00h	14h	75 %	125 ns	8	1
00h	23h	62 %	125 ns	8	1
00h	32h	50 %	125 ns	8	1
01h	01h	75 %	250 ns	4	1
01h	10h	50 %	250 ns	4	1
40h	14h	75 %	125 ns	8	2
40h	23h	62 %	125 ns	8	2

CAN FD

BTR 0	BTR 1	Sample Point	Tq	Nq	SJW
00h	05h	88 %	125 ns	8	1
00h	14h	75 %	125 ns	8	1
00h	23h	62 %	125 ns	8	1
00h	32h	50 %	125 ns	8	1
01h	01h	75 %	250 ns	4	1
01h	10h	50 %	250 ns	4	1
40h	14h	75 %	125 ns	8	2
40h	23h	62 %	125 ns	8	2

CAN interface

List entry in Available Hardware

USB Interface, 1-channel

see example above

USB Interface, 2-channel

PCAN-USB Pro FD: Device ID 251181Fh, Channel 1

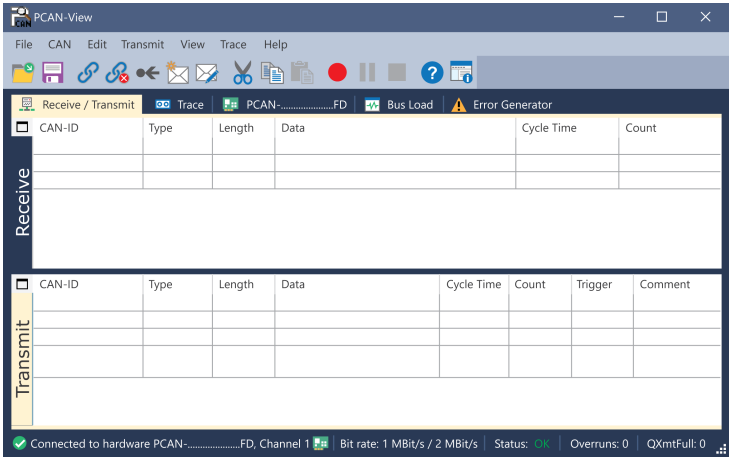
PCAN-USB Pro FD: Device ID 251181Fh, Channel 2

PCIe Interface, 2-channel

PCAN-PCI Express at PCI Bus 1, Device 0, Channel 1

PCAN-PCI Express at PCI Bus 1, Device 0, Channel 2

2. If there are several CAN interfaces, select the desired interface. For multiple channels, select the desired channel from the list.
3. Enter the *bit rate(s)* and other settings according to the connected CAN bus.
4. Confirm the entries with *OK*. The main window appears and displays the *Receive / Transmit* tab.



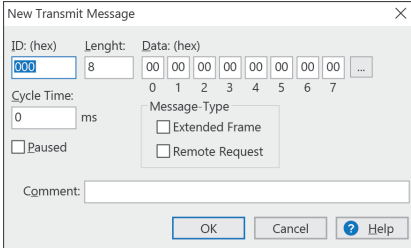
5. For initializing another channel or CAN interface, open another instance of *PCAN-View*.

5.2 Transmit CAN message

1. Select the menu command *Transmit / New Message*.

Depending on the CAN interface, the dialog box *New Transmit Message* is displayed with or without settings for CAN FD.

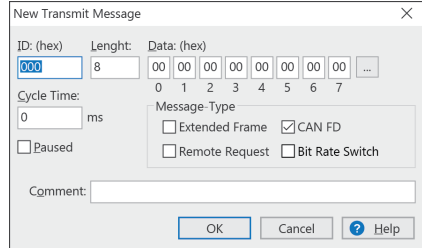
CAN



The dialog box 'New Transmit Message' for the CAN interface contains the following fields and options:

- ID: (hex)**: A text box containing '000'.
- Length:**: A text box containing '8'.
- Data: (hex)**: A row of eight hex digit boxes (00, 00, 00, 00, 00, 00, 00, 00) followed by an ellipsis.
- Cycle Time:**: A text box containing '0' followed by 'ms'.
- Message-Type**: Two checkboxes, 'Extended Frame' and 'Remote Request', both of which are unchecked.
- Paused**: An unchecked checkbox.
- Comment:**: An empty text box.
- Buttons**: 'OK', 'Cancel', and 'Help' (with a question mark icon).

CAN FD



The dialog box 'New Transmit Message' for the CAN FD interface contains the following fields and options:

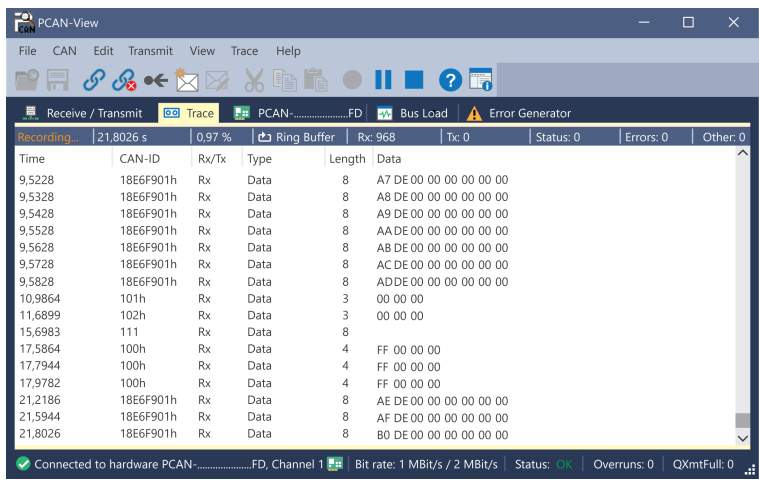
- ID: (hex)**: A text box containing '000'.
- Length:**: A text box containing '8'.
- Data: (hex)**: A row of eight hex digit boxes (00, 00, 00, 00, 00, 00, 00, 00) followed by an ellipsis.
- Cycle Time:**: A text box containing '0' followed by 'ms'.
- Message-Type**: Three checkboxes: 'Extended Frame' (unchecked), 'CAN FD' (checked), and 'Remote Request' (unchecked). There is also an unchecked checkbox for 'Bit Rate Switch'.
- Paused**: An unchecked checkbox.
- Comment:**: An empty text box.
- Buttons**: 'OK', 'Cancel', and 'Help' (with a question mark icon).

1. Enter the *ID*, *Length* and *Data* of the message. Other settings can be made according to the connected CAN bus.
2. Enter a value into the *Cycle Time* field to choose manually or periodically message transmission.
To transmit periodically enter a value greater than 0.
To transmit only manually enter the value 0.
3. Confirm the entries with *OK*.
The created transmit message appears on the *Receive / Transmit* tab.
4. To send the message manually, select the menu command *Transmit > Send* or press the **space** bar.
The manual transmission process is performed additionally for periodically transmitted CAN messages.

5.3 Additional Tabs

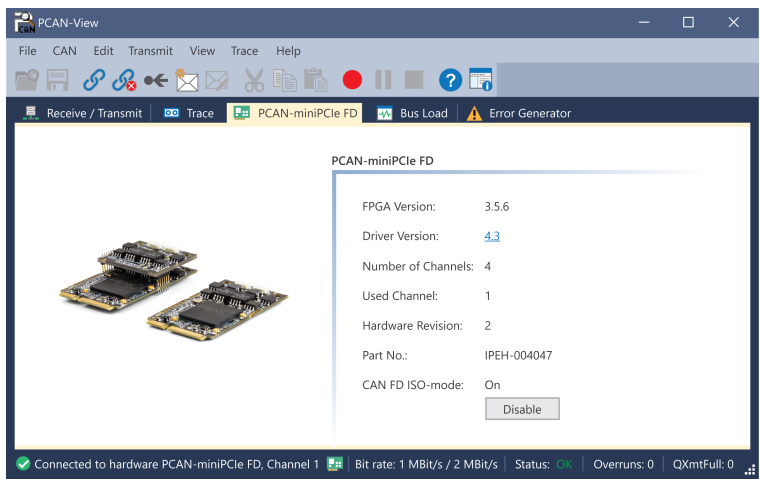
Depending on the CAN interface, additional tabs are available.

5.3.1 Trace Tab



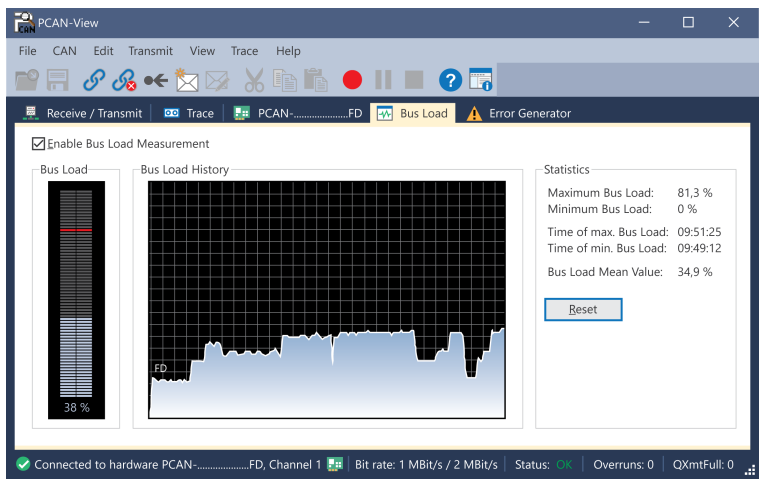
The tracer (data logger) records the communication of the CAN bus in linear or ring buffer mode. The trace data can be saved to a file.

5.3.2 CAN Interface Tab



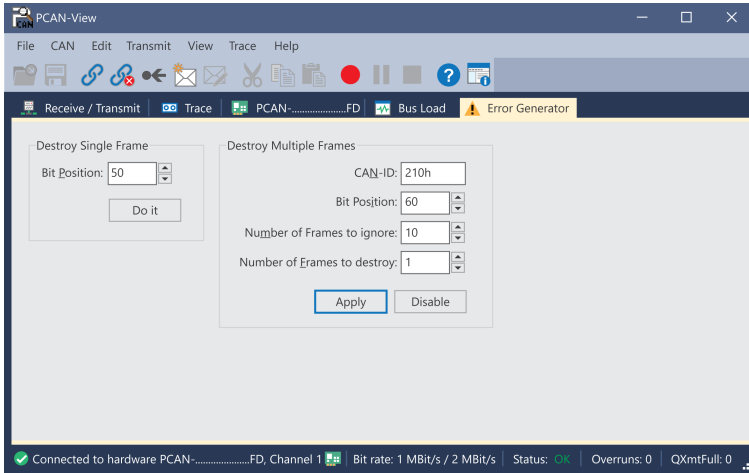
The *CAN interface* tab shows information about the hardware and the used Windows device driver. In this case exemplary for the PCAN-miniPCIe FD. Depending on the CAN interface, a hardware ID can be determined to distinguish several interfaces of the same type. For interfaces with CAN FD a transmission according to "ISO" or "Non-ISO" can be set as default of the hardware.

5.3.3 Bus Load Tab



The *Bus Load* tab displays the current bus load, its time history and statistical information of the connected CAN channel.

5.3.4 Error Generator Tab



Via the *Error Generator* tab the communication on the CAN bus in test environments or during the development of CAN buses can be disturbed in a controlled way by 6 consecutive dominant bits. This is a violation of the CAN protocol on the CAN bus which must be recognized as an error by the connected CAN nodes.



Note: The Error Generator should only be used by experienced users and in the development environment. For further information, please contact our customer support: support@peak-system.com

You can destroy CAN frames with the error generator by one of two methods:

- once after activation
- repeatedly at specific intervals related to a CAN ID

Destroy Single CAN Frame

The *Destroy Single Frame* area refers to the next CAN frame that is recognized after activation.

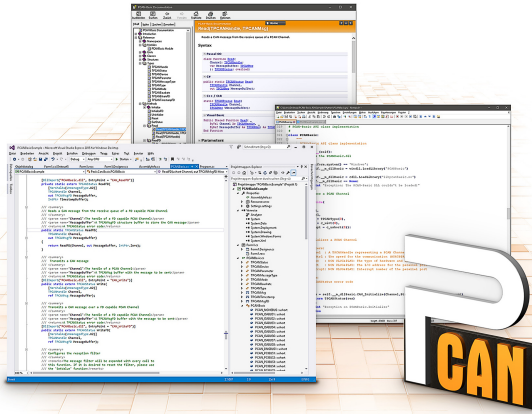
1. Enter the *Bit Position* where in the CAN frame the error is to be generated. The bit position must start after the identifier. The count includes the stuff bits.
2. Execute the destroy action with *Do it*.

The next received or transmitted CAN frame will be destroyed at the selected bit position.

Destroy Multiple CAN Frames

1. Enter the *CAN ID* of the CAN frame that is intended to be destroyed multiple times. The following specifications refer to this ID.
2. Enter the *Bit Position* where in the CAN frame the error is to be generated. The bit position must start after the identifier. The count includes the stuff bits.
3. If CAN messages are to be sent unharmed before being destroyed, specify the *Number of Frames to ignore*.
4. Determine the *Number of Frames to destroy*.
5. Confirm the entries with *Apply* to activate the error generator.
6. Stop destroying further CAN frames with *Disable*.

6 API PCAN-Basic



The intended use of PCAN-Basic requires compliance with the license rights. Read the license agreement for end users at:

<https://www.peak-system.com/quick/eula>

The programming interface (API) PCAN-Basic provides basic functions for the connection of own programs to the CAN and CAN FD Interfaces of PEAK-System. PCAN-Basic is the interface between the program and the device driver. In Windows operating systems this is a DLL (Dynamic Link Library) and in Linux operating systems an SO (Dynamic Shared Object). PCAN-Basic is designed to be cross-operating system compatible. Software projects can be ported between supported systems with little effort.

With the installation of the device driver package under Windows the DLL files of the API PCAN-Basic are placed in the system folder. Examples for all common programming languages as well as libraries and help files are available as a download package at: www.peak-system.com/quick/DL-Develop-E

For Linux, a download of the API is available under this link. For a use of PCAN-Basic another driver package with a chardev driver is needed, because an access under SocketCAN is not possible. The "Driver Package for Proprietary Purposes", the user manual, and further information about the implementation can be found at www.peak-system.com/linux.

6.1 Features of PCAN-Basic

- API for developing applications with CAN and CAN FD connections
- Support for CAN specifications 2.0 A/B and FD
- Application development for the platforms Windows 11 (x64/ARM64), 10 (x64), and Linux
- Multiple PEAK-System applications and your own can be operated on a physical channel at the same time
- Use of a single DLL for all supported hardware types
- Use of up to 16 channels for each hardware type (depending on the PEAK CAN interface used)
- Simple switching between channels of a PEAK CAN interface
- Access to the CAN channels of a PCAN-Gateway via the new PCAN-LAN hardware type
- Driver-internal buffering of up to 32,768 CAN messages per CAN channel
- Precision of time stamps on received messages up to 1 μ s (depending on the PEAK CAN interface used)
- Supports PEAK-System's trace formats version 1.1 and 2.0 (for CAN FD applications)
- Access to specific hardware parameters, such as listen-only mode
- Notification of the application through Windows® events when a message is received
- Support of CAN error frames
- Confirmation of physical transmission by CAN echo frames
- Extended system for debugging operations
- Multilingual debugging output
- Output language depends on operating system
- Debugging information can be defined individually
- Thread-safe API

6.2 Principle Description of the API

The sequence of accessing the CAN interface is divided into three phases:

Initialization

A CAN channel must be initialized before using it. This is done by the simple call of the function `CAN_Initialize` for CAN and `CAN_InitializeFD` for CAN FD. Depending on the type of the CAN hardware, up to 16 CAN channels can be opened at the same time. After a successful initialization the CAN channel is ready. No further configuration steps are required.

Interaction

For receiving and transmitting messages the functions `CAN_Read` and `CAN_Write` as well as `CAN_ReadFD` and `CAN_WriteFD` are available depending on the initialization mode. Additional settings can be made, such as setting up message filters to confine to specific CAN IDs or setting the CAN controller to Listen-only mode.

When receiving CAN messages, events are used for an automatic notification of an application (client). This offers the following advantages:

- The application no longer needs to check for received messages periodically (no polling).
- The response time at reception is reduced.

Completion

To end the communication the function `CAN_Uninitialize` is called in order to release the reserved resources for the CAN channel, among others. In addition the CAN channel is marked as "Free" and is available to other applications.

7 Technical Data

Connections

CAN slot bracket	Connection side	Connection type
	CAN bus	D-Sub (m), 9-pin, pin assignment according to CiA® 106
	CAN interface	10-pin connector
PCIe/104	PCIe/104, PCI Express x1 (1 lane); Stack-through PCI/104 bus, optionally equipped with contact strip on request	

CAN

Protocols	CAN according to ISO 11898-1		
Physical transmission	ISO 11898-2 (High-speed CAN)		
Transceiver	NXP PCA82C251		
CAN bit rates	5 kbit/s to 1 Mbit/s		
Controller	FPGA implementation (SJA1000 compatible)		
Time stamp resolution	1 µs		
Galvanic isolation	Single Channel		without
	Dual Channel		without
	Single Channel	opto-decoupled	up to 500 V, separate for each CAN connector
	Dual Channel	opto-decoupled	up to 500 V, separate for each CAN connector
	Quad Channel	opto-decoupled	up to 500 V, separate for each CAN connector
Power supply external devices at D-Sub pin 1 and/or pin 9 (not assigned at delivery)	Single Channel		5 V, max. 100 mA
	Dual Channel		5 V, max. 100 mA
	Single Channel	opto-decoupled	5 V, max. 50 mA
	Dual Channel	opto-decoupled	5 V, max. 50 mA
	Quad Channel	opto-decoupled	5 V, max. 50 mA
Internal Termination	none		

Power supply

Supply voltage	5 V DC		
Max. current consumption without power supply for external devices	Single Channel		360 mA
	Dual Channel		420 mA
	Single Channel	opto-decoupled	360 mA
	Dual Channel	opto-decoupled	420 mA
	Quad Channel	opto-decoupled	550 mA

Measures

Size absolute (W x L x H)	90.2 x 95.9 x 21.8 mm		
Weight	Single Channel		42 g
	Dual Channel		47 g
	Single Channel	opto-decoupled	44 g
	Dual Channel	opto-decoupled	50 g
	Quad Channel	opto-decoupled	56 g
	Slot bracket	Single Channel	25 g
	Slot bracket	Dual Channel	40 g

Environment

Operating temperature	-40 to +85 °C (-40 to +185 °F)
Temperature for storage and transport	-40 to +125 °C (-40 to +257 °F)
Relative humidity	15 to 90 %, not condensing

Conformity

RoHS	EU Directive 2011/65/EU (RoHS 2) + 2015/863/EU DIN EN IEC 63000:2019-05
EMC	EU Directive 2014/30/EU DIN EN 55032:2022-08 DIN EN 55035:2018-04

Appendix A CE Certificate

EU Declaration of Conformity



This declaration applies to the following product:

Product name: **PCAN-PCI/104-Express**
Item number(s): **IPEH-003054, IPEH-003055, IPEH-003056, IPEH-003057, IPEH-003058**
Manufacturer: **PEAK-System Technik GmbH**
Otto-Röhm-Straße 69
64293 Darmstadt
Germany



We declare under our sole responsibility that the mentioned product is in conformity with the following directives and the affiliated harmonized standards:

EU Directive 2011/65/EU (RoHS 2) + 2015/863/EU (amended list of restricted substances)

DIN EN IEC 63000:2019-05

Technical documentation for the assessment of electrical and electronic products with respect to the restriction of hazardous substances (IEC 63000:2016);
German version of EN IEC 63000:2018

EU Directive 2014/30/EU (Electromagnetic Compatibility)

DIN EN 55032:2022-08

Electromagnetic compatibility of multimedia equipment - Emission requirements (CISPR 32:2015);
German version of EN 55032:2015 + AC:2016 + A11:2020 + A1:2020

DIN EN 55035:2018-04

Electromagnetic compatibility of multimedia equipment - Immunity requirements (CISPR 35:2016, modified);
German version of EN 55035:2017

Darmstadt, 31 August 2023

A handwritten signature in black ink, appearing to read "Uwe Wilhelm".

Uwe Wilhelm, Managing Director

Appendix B UKCA Certificate

UK Declaration of Conformity



This declaration applies to the following product:

Product name: **PCAN-PCI/104-Express**

Item number(s): **IPEH-003054, IPEH-003055, IPEH-003056, IPEH-003057,
IPEH-003058**

Manufacturer:

PEAK-System Technik GmbH
Otto-Röhm-Straße 69
64293 Darmstadt
Germany

UK authorized representative:

Control Technologies UK Ltd
Unit 1, Stoke Mill,
Mill Road, Sharnbrook,
Bedfordshire, MK44 1NN, UK



We declare under our sole responsibility that the mentioned product is in conformity with the following UK legislations and the affiliated harmonized standards:

The Restriction of the Use of Certain Hazardous Substances in Electrical and Electronic Equipment Regulations 2012

DIN EN IEC 63000:2019-05

Technical documentation for the assessment of electrical and electronic products with respect to the restriction of hazardous substances (IEC 63000:2016);
German version of EN IEC 63000:2018

Electromagnetic Compatibility Regulations 2016

DIN EN 55032:2022-08

Electromagnetic compatibility of multimedia equipment - Emission requirements
(CISPR 32:2015);
German version of EN 55032:2015 + AC:2016 + A11:2020 + A1:2020

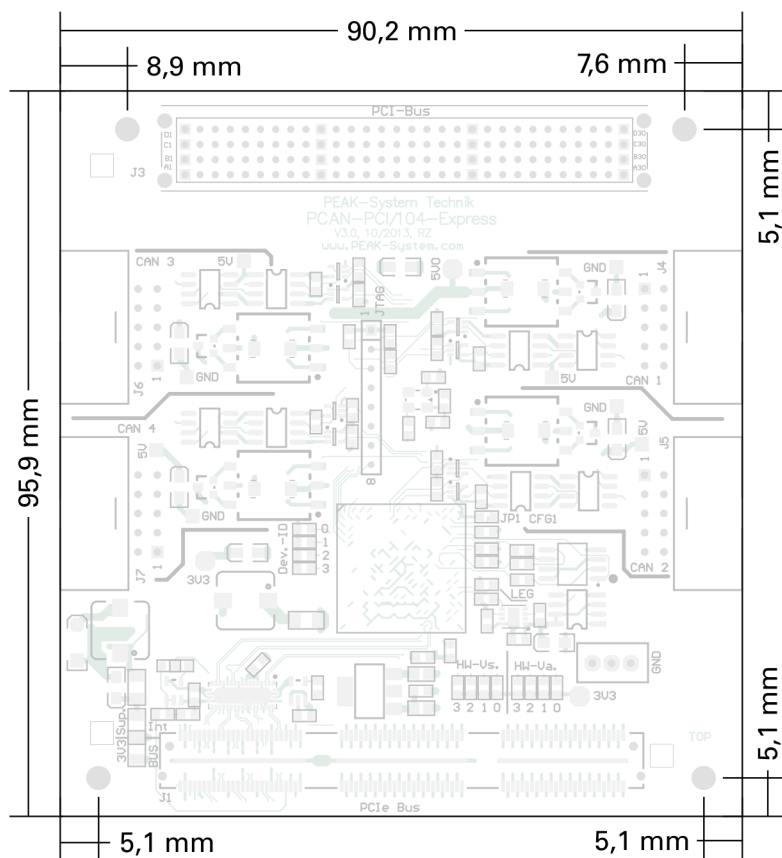
DIN EN 55035:2018-04

Electromagnetic compatibility of multimedia equipment - Immunity requirements
(CISPR 35:2016, modified);
German version of EN 55035:2017

Darmstadt, 31 August 2023

Uwe Wilhelm, Managing Director

Appendix C Dimension Drawings



Appendix D Quick Reference

Software/Hardware Installation under Windows

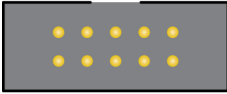
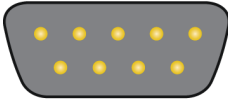
Download the device drivers installation package from our website www.peak-system.com/quick/DL-Driver-E. Install the driver before you install the CAN interface.

The new hardware is detected at the next Windows start and the driver is initialized. Check the operational readiness. Open the Windows Start menu. Type `Peak Settings` and press `Enter`. The window *PEAK settings* appears. The connected CAN interface is displayed under *CAN Hardware*.

Getting Started under Windows

Run the CAN monitor PCAN-View from the Windows Start menu as a sample application for accessing the CAN interface. For initialization of the CAN interface select the desired CAN channel and CAN bit rate.

Pin assignment

10-pin connector on CAN interface	D-Sub plug on slot bracket, 9-pin	Assignment
<div><div>97531</div><div>108642</div></div>	<div><div>12345</div><div>6789</div></div>	
2	6	GND
3	2	CAN_Low
4	7	CAN_High
5	3	GND
8	9	+5 V (optional)
1, 6, 7, 9, 10	1, 4, 5, 8	None

Appendix E Linux

Depending on the Kernel version, device drivers for the CAN interfaces from PEAK-System are already included in the operating system. The PCAN interfaces are handled as network devices (SocketCAN, netdev). You can find the documentation for SocketCAN under:

<https://www.kernel.org/doc/Documentation/networking/can.txt>

The following command lists the available drivers:

```
grep PEAK_ /boot/config-`uname -r`
```

Whether the required driver for the PCAN interface is present and loaded can be checked with the following command:

```
lsmod | grep ^peak check
```

If the initialization was successful, the response line starts with `peak_pci`.

You can find a recent list of which PCAN interface is supported from which kernel version onwards on our Linux website.

If the required drivers are not listed, install the "Driver Package for Proprietary Purposes". The download and documentation for the driver can also be found on: www.peak-system.com/linux

This driver package is also needed to use the APIs based on the chardev driver, for example PCAN-Basic, libpcan, or libpcanfd.

Appendix F Disposal

The product must not be disposed of in household waste. Dispose of the product properly in accordance with local regulations.